



Systems Thinking

Modularization-2: Instruction Set and Instruction Pipeline

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Outline

- What is systems thinking?
- Three objectives of systems thinking
- Abstraction
- Modularization
 - Modularization and modules
 - Combinational circuits
 - Sequential circuits
 - Instruction Set and Instruction Pipeline
 - Design a simple instruction set
 - Executing instructions by an instruction pipeline
 - Software Stack
- Seamless transition

These slides acknowledge sources for additional data not cited in the textbook

4.4 Instruction set and instruction pipeline

- 1-minute quiz
 - Q1: **Combinational circuits vs. Boolean expressions**
What are the relationships between combinational circuits and Boolean expressions?

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 - Q1: **Combinational circuits vs. Boolean expressions**
What are the relationships between combinational circuits and Boolean expressions?
 - A1: Combinational circuits are equivalent to and implement Boolean expressions

4.4 Instruction set and instruction pipeline

- 1-minute quiz
 - Q1: **Combinational circuits vs. Boolean expressions**
What are the relationships between combinational circuits and Boolean expressions?
 - A1: Combinational circuits are equivalent to and implement Boolean expressions
- Remarks
 - For any combinational circuit, there is an equivalent Boolean expression
 - And vice versa
 - Here, equivalence means they both have the same truth table
 - A combinational circuit implements a Boolean expression
 - By a logic diagram of gates

4.4 Instruction set and instruction pipeline

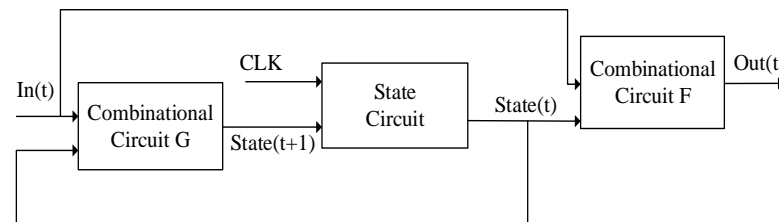
- 1-minute quiz
 - Q2: Sequential circuits vs. automata
What are the relationships between sequential circuits and automata?

4.4 Instruction set and instruction pipeline

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4.4 Instruction set and instruction pipeline

- 1-minute quiz
 - Q2: Sequential circuits vs. automata
What are the relationships between sequential circuits and automata?
 - A2: Sequential circuits are equivalent to and implement automata
- Remarks
 - For any sequential circuit, there is an equivalent automaton
 - And vice versa
 - Here, equivalence means they both have the same state transition table and initial conditions
 - A sequential circuit implements a automaton
 - By a logic diagram of a state circuit and two combinational circuits



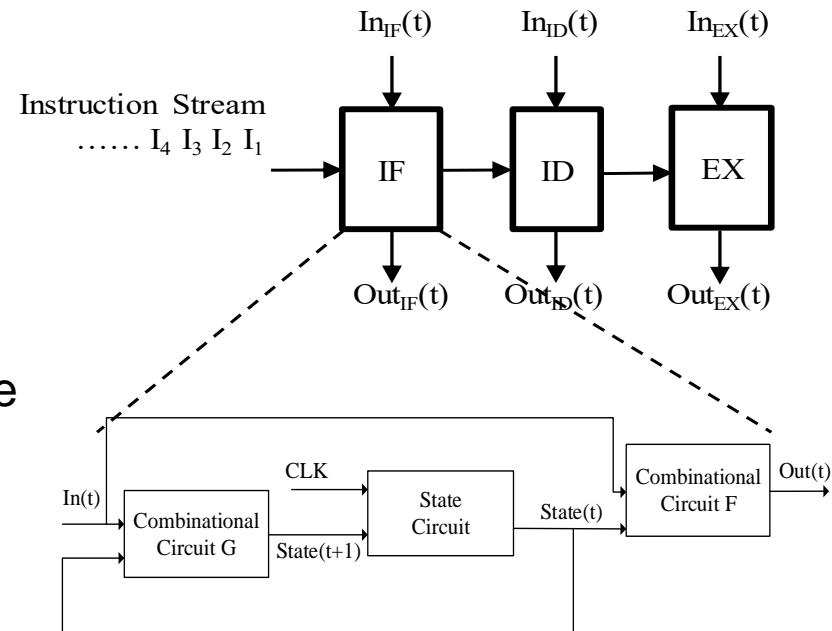
4.4 Instruction set and instruction pipeline

- Automata (sequential circuits) are basic concepts, widely used in computers and application systems
- A processor (CPU) is implemented as a group of sequential circuits
 - Instruction pipeline is the basic hardware abstraction to execute instructions
 - Each stage of the instruction pipeline is a sequential circuit

- Example

- The 3-stage instruction pipeline (when executing instruction MOV 0, R1)

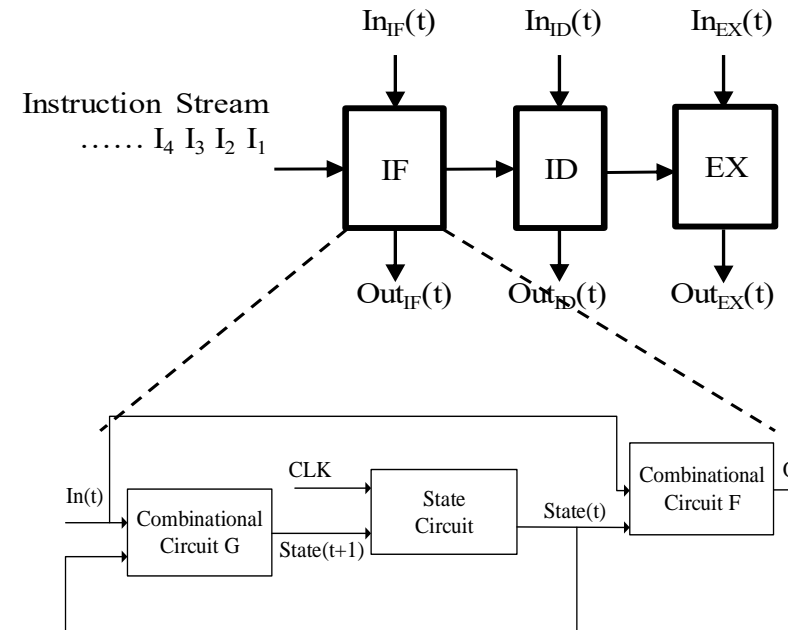
- **Instruction Fetch** (IF) stage: $IR \leftarrow M[PC]$
 - Fetch an instruction from the memory cell $M[PC]$ to the Instruction Register of CPU
 - **Instruction Decode** (ID): $\text{Control Signals} = \text{Decode}(IR)$
 - Decode the instruction to generate control signals
 - **Instruction Execute** (EX): $R1 \leftarrow 0; PC \leftarrow PC+1$
 - Execute the instruction according to the control signals, and increment PC



A 3-stage instruction pipeline is implemented as 3 sequential circuits

4.4 Instruction set and instruction pipeline

- Automata (sequential circuits) are basic concepts, widely used in computers and application systems
- A processor (CPU) is implemented as a group of sequential circuits
 - Instruction pipeline is the basic hardware abstraction to execute instructions
 - Each stage of the instruction pipeline is a sequential circuit
- The 3-stage instruction pipeline can execute instructions in overlapped mode, thus increase clock frequency
 - E. g., 1 GHz \rightarrow 3 GHz
 - See pipelining when discussing Amdahl's law



A 3-stage instruction pipeline is implemented as 3 sequential circuits
Practical CPUs have 5~31 pipeline stages

4.4.1 Design the instruction set of FC

- The Fibonacci Computer (FC) executes only the following code (shown in both Go and assembly language notations)
 - Recall Section 2.3 in textbook

fib[0] = 0	MOV 0, R1	
	MOV R1, M[R0]	//R0=12 initially
fib[1] = 1	MOV 1, R1	
	MOV R1, M[R0+8]	
for i := 2; i < 51; i++ {	MOV 2, R2	// i:=2
fib[i] = fib[i-1] + fib[i-2]	MOV 0, R1	// label Loop
	ADD M[R0+R2*8-16], R1	
	ADD M[R0+R2*8-8], R1	
	MOV R1, M[R0+R2*8-0]	
	INC R2	// i++
	CMP 51, R2	// i < 51?
}	JL Loop	// if Yes, goto Loop

- Design an instruction set for FC
 - Any instruction consists of an opcode and one or more operands
 - E.g., **opcode** **operand** **operand**
 - In mnemonics, e.g., **MOV 0, R1**
 - In binary, e.g., **000 000000 01**

Design Process

- FC has a memory and five registers
 - FLAGS: CPU status register
 - Holding status value of instruction execution, such as if the result is overflow, zero, less than, etc.
 - Only “less than” is used in this example
 - PC: program counter
 - Holding the address of the next instruction to be executed
 - R0, R1, and R2: general purpose registers
 - Holding operands of instructions
- Determine the types of instructions and decide the opcodes (one for a type)
 - Merge similar instructions into a type
 - E.g., There are three distinct instructions moving an immediate value to a register
 - MOV 0, R1; MOV 1, R1; MOV 2, R2
 - They belong to one type of instruction

```
fib[0] = 0      MOV 0, R1
                MOV R1, M[R0]
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for i := 2; i < 51; i++ {
    fib[i] = fib[i-1] + fib[i-2]
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                INC R2
                CMP 51, R2
                JL Loop
}
```

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- FC has a memory and five registers
 - FLAGS, PC, R0, R1, and R2
- Determine the types of instructions and decide the opcodes (one for a type)
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 - E.g., 3 instructions move an immediate value to a register
 - MOV 0, R1; MOV 1, R1; MOV 2, R2
 - They belong to one type of instruction
- There are six types of instructions

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for i := 2; i < 51; i++ {
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MOV 0, R1
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MOV R1, M[R0+8]
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MOV R1, M[R0+R2*8-0]
INC R2
CMP 51, R2
JL Loop

Instruction Type	Opcode	Semantics
MOV to Register	000	Assign an immediate value to a register
MOV to Memory	001	Assign the content of a register to M[Address]
ADD	010	$R1 + M[Address] \rightarrow R1$
INC	011	$R + 1 \rightarrow R$ (R is a register)
CMP	100	Compare to a value, assign the result to FLAGS
JL	101	If FLAGS is '<' (less than), Loop \rightarrow PC

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 JL Loop ✓

Need 3 bits for the opcodes

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Design Process

- FC has a memory and five registers
 - FLAGS, PC, R0, R1, and R2
- Determine the types of instructions and decide the opcodes
- For each opcode, determine its operands

```

fib[0] = 0      MOV 0, R1
                MOV R1, M[R0]
fib[1] = 1      MOV 1, R1
                MOV R1, M[R0+8]
for i := 2; i < 51; i++ {
    fib[i] = fib[i-1] + fib[i-2]
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                ADD M[R0+R2*8-8], R1
                MOV R1, M[R0+R2*8-0]
                INC R2
                CMP 51, R2
            }
                JL Loop
    
```

In practice, assume 8, 16, 32 or 64 bits

- Assuming the instruction length = 11 bits
- There are 3 data registers, needing 2 bits
- Leave 6 bits for immediate value
- The base+index+offset mode
 - Address = $R0 + R2 * I + J$, where
 - R0, R2 are fixed
 - $I = 0, 1, 2, 4, 8$
 - $J = 0, \pm 4, \pm 8, \pm 16$
 - $5 \times 7 = 35$ possible (I, J) pairs
 - $35 < 2^6$, 6 bits are enough

Notes

- For INC R2, operand 1 can be any value
- JL has only one operand

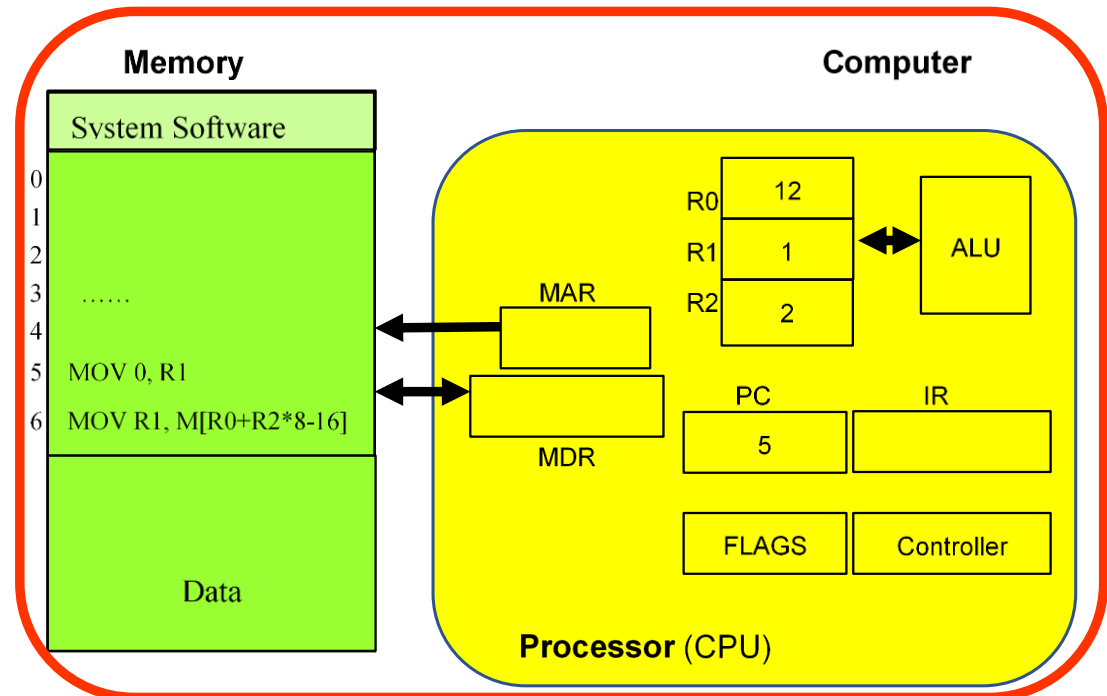
Opcode	Operand 1	Operand 2	Instruction
3-bit	Immediate Value, 6-bit	Register, 2-bit	
000	000000	01	MOV 0, R1
000	000001	01	MOV 1, R1
000	000010	10	MOV 2, R2
011	111111	10	INC R2
100	110011	10	CMP 51, R2
101	00000101		JL Loop
Opcode	Operand 1	Operand 2	Instruction
3-bit	Memory Address, 6-bit	Register, 2-bit	
001	$R0 + R2 * 0 + 0$	01	MOV R1, M[R0]
001	$R0 + R2 * 0 + 8$	01	MOV R1, M[R0+8]
001	$R0 + R2 * 0 - 0$	01	MOV R1, M[R0+R2*8-0]
010	$R0 + R2 * 8 - 8$	01	ADD M[R0+R2*8-8], R1
010	$R0 + R2 * 8 - 16$	01	ADD M[R0+R2*8-16], R1

4.4.2 Look inside a processor

- To see an example of executing instruction MOV 0, R1
 - by a 3-stage instruction pipeline
 - Instruction Fetch (IF): $IR \leftarrow M[PC]$
 - Instruction Decode (ID): Signals = Decode(IR)
 - Instruction Execute (EX): $R1 \leftarrow 0; PC \leftarrow PC+1$

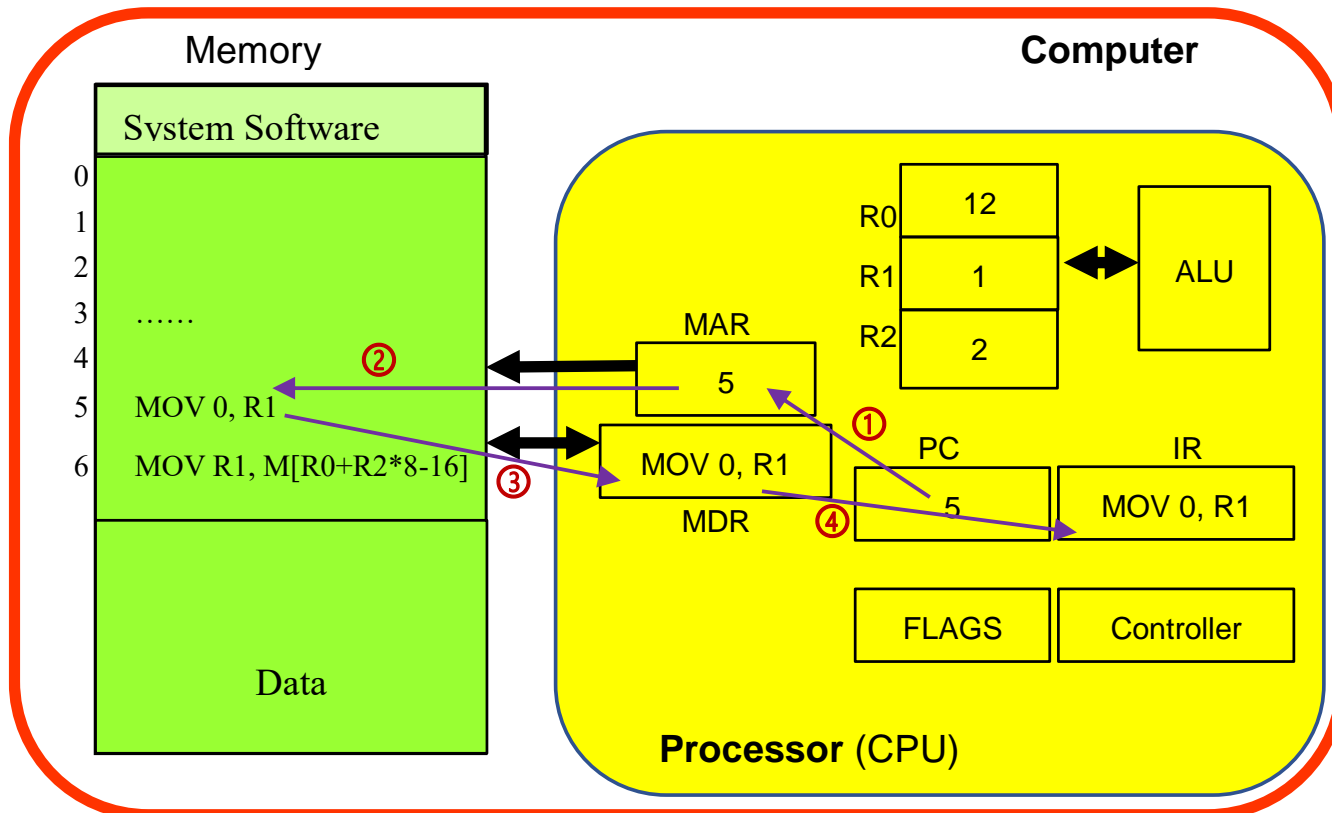
- Internal components not visible to user

- **IR: Instruction Register** holding the instruction being executed
- **MAR: Memory Address Register**, holding the memory address used
- **MDR: Memory Data Register**, holding the data for a load or store
- Controller: control circuit to generate control signals



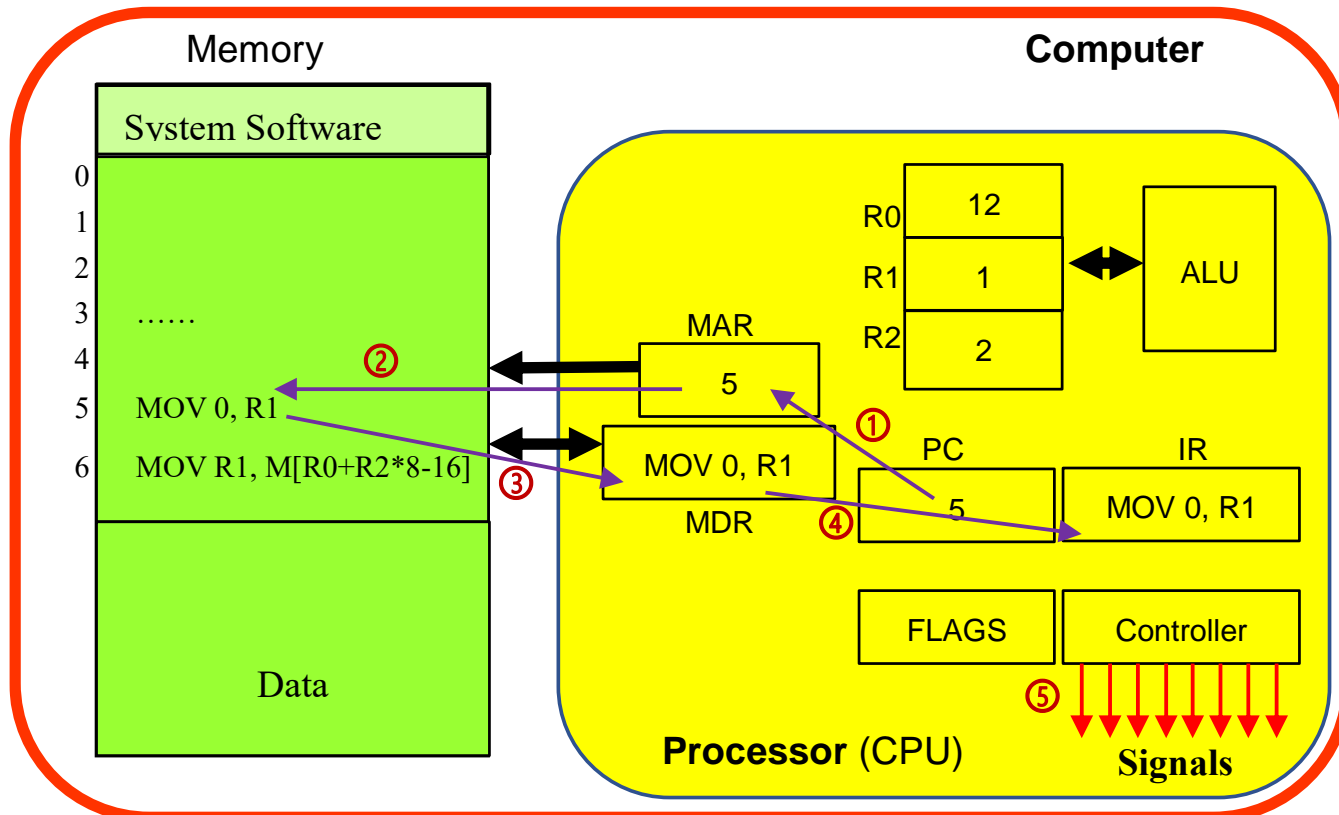
Execution details

- After IF stage (micro operations ① ② ③ ④)



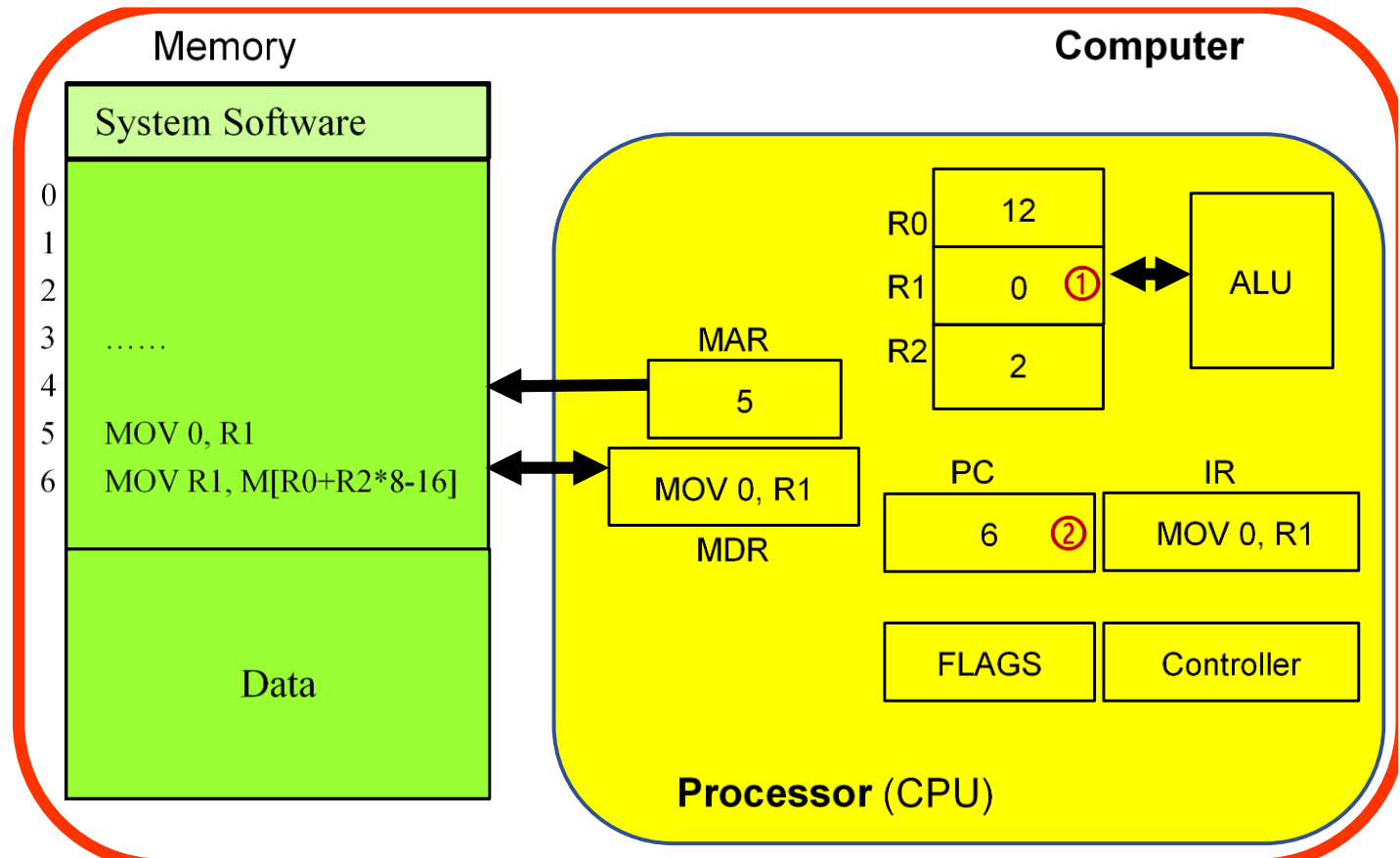
Execution details

- After IF stage (micro operations ① ② ③ ④)
- After ID stage (micro operation ⑤)



Execution details

- After EX stage (micro operations ① ②)
 - $0 \rightarrow R1$; $PC+1 \rightarrow PC$



4.5 Software Stack on a von Neumann Computer

- Software is organized as a layered structure, called **software stack**
 - Upper layers use lower layers, utilizing the modularization and reuse advantages
- Notes
 - Middleware: between application software and system software
 - Firmware stored in ROM (**why**), e.g., BIOS (the Basic Input/Output System)
 - Software comes in **source code** form **binary code** form

Software Type			Example
Application Software			Scientific computing, Business computing, Personal productivity software; fib.dp.go , myPage.html PDF, Search Engine, TikTok, WeChat
Infrastructure Software	Middleware	Databases, Web servers, Web Browsers	MySQL, Nginx, WebServer.go Chrome, Safari
	System Software	Languages, Compilers, Interpreters	C, Go , JavaScript , Python Shell
		Operating Systems	Linux , Android, iOS, Windows
		Firmware	BIOS
von Neumann Architecture			
Hardware			

Students
use
software
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and
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